

Incorrect Proofs and Epsilon Calculus ¹

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- 1 Incorrect Proofs
- 2 Weakest Precondition
- 3 Change of Paradigm: From Preconditions to Proofs
- 4 Epsilon Calculus
- 5 Flow of Errors via Epsilon Calculus
- 6 False-Tolerance

Incorrect Proofs

Euler's Incorrect Basel Problem Proof

Euler became famous by deriving

$$\frac{1}{8} \sum_{\mathbf{r}} \frac{1}{r^2} = \frac{6}{\pi^2} \quad (1)$$

Let us consider Eulers reasoning.

Euler's Incorrect Basel Problem Proof

Consider the polynomial of even degree

$$b_0 - b_1x^2 + b_2x^4 - \dots + (-1)^n b_n x^{2n} \quad (2)$$

If $b_n = 1$ it has the $2n$ roots $\pm\beta_1, \dots, \beta_n \neq 0$ then (2) can be written as

$$(x - \beta_1)(x + \beta_1) \dots (x - \beta_n)(x + \beta_n) \quad (3)$$

$$(-1)^n (\beta_1 - x)(\beta_1 + x) \dots (\beta_n - x)(\beta_n + x) \quad (4)$$

$$(-1)^n (\beta_1^2 - x^2) \dots (\beta_n^2 - x^2) \quad (5)$$

where $b_0 = (-1)^n \beta_1^2 \dots \beta_n^2$

$$b_0 \left(1 - \frac{x^2}{\beta_1^2}\right) \left(1 - \frac{x^2}{\beta_2^2}\right) \dots \left(1 - \frac{x^2}{\beta_n^2}\right) \quad (6)$$

By comparing coefficients in (2) and (6) one obtains that

$$b_1 = b_0 \left(\frac{1}{\beta_1^2} + \frac{1}{\beta_2^2} + \dots + \frac{1}{\beta_n^2} \right). \quad (7)$$

Euler's Incorrect Basel Problem Proof

Next Euler considers the Taylor series for $\sin(x)$ divided by x

$$\frac{\sin x}{x} = \sum_{n=0}^{\infty} (-1)^n \frac{x^{2n}}{(2n+1)!} \quad (8)$$

which has as roots $\pm\pi, \pm2\pi, \pm3\pi, \dots$. Now by way of analogy Euler **assumes** that the infinite degree polynomial (8) behaves in the same way as the finite polynomial (2). Hence in analogy to (6) he obtains

$$\frac{\sin x}{x} = \left(1 - \frac{x^2}{\pi^2}\right) \left(1 - \frac{x^2}{4\pi^2}\right) \left(1 - \frac{x^2}{9\pi^2}\right) \dots \quad (9)$$

and in analogy to (7) he obtains

$$\frac{1}{3!} = \left(\frac{1}{\pi^2} + \frac{1}{4\pi^2} + \frac{1}{9\pi^2} + \dots\right) \quad (10)$$

which immediately gives

$$\sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{\pi^2}{6}$$

Weakest Precondition

What is a Weakest Precondition?

Goal: Given a satisfiable formula B , find the weakest satisfiable A in the language of B such that $A \supset B$ is valid.

Definition: A precondition for a satisfiable formula B is any formula A such that $A \supset B$ is valid. We define order among the satisfiable preconditions as $K < C$, meaning that $K \supset C$ is valid but $C \supset K$ is not valid. A formula A is a *weakest precondition* for B if:

- $A \supset B$ is valid
- A is satisfiable
- A is $<$ - minimal

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- $A \supset B$ is valid
- A is satisfiable
- A is $<$ - minimal

Observation:

- $\perp \supset B$ is always valid, therefore we exclude $\perp$ when searching for weakest preconditions.
- $<$ might not be linear

What is a Weakest Precondition?

Proposition: For a propositional formula A which is satisfiable, weakest preconditions are calculable as minimal conjunctions.

Example

A	B	C	$(A \vee (B \supset C)) \wedge (A \supset B)$
0	0	0	1
0	0	1	1
0	1	0	0
0	1	1	1
1	0	0	0
1	0	1	0
1	1	1	1
1	1	0	1

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1	0	0	0
1	0	1	0
1	1	1	1
1	1	0	1

Among the weakest pre-conditions are:

- $(\neg A \wedge \neg B \wedge \neg C)$
- $(\neg A \wedge \neg B \wedge C)$
- $(\neg A \wedge B \wedge C)$
- $(A \wedge B \wedge \neg C)$
- $(A \wedge B \wedge C)$

Failure of Weakest Preconditions in First-Order Logic

First-Order Logic: Quantifiers introduce non-terminating implication chains.

Example

$$\forall x (A(p(x)) \supset A(x)) \supset A(0)$$

- $A(0), A(p(0)), A(p(p(0))) \dots$ are all preconditions, but none of them is weakest.
- These preconditions form an infinite descending chain under implication, i.e., each is strictly weaker than the previous one.

Conclusion: Quantification breaks finite precondition minimality.

Change of Paradigm: From Preconditions to Proofs

Instead of considering incorrect expressions, we consider incorrect proofs of correct and incorrect expressions.

From Preconditions to Proofs

Example

$$\begin{array}{c} (\forall x(A(x) \wedge \exists yB(y)) \rightarrow \forall xA(x)) \wedge \exists xC(x). \\ \hline \frac{A(a) \Rightarrow A(a) \quad \exists yB(y) \Rightarrow \exists yB(y)}{A(a) \wedge \exists yB(y) \Rightarrow A(a)} \quad * \\ \hline \frac{\forall x(A(x) \wedge \exists yB(y)) \Rightarrow A(a) \quad A(a) \wedge \exists yB(y) \Rightarrow \exists yC(y)}{\forall x(A(x) \wedge \exists yB(y)) \Rightarrow \forall xA(x) \quad \forall x(A(x) \wedge \exists yB(y)) \Rightarrow \exists yC(y)} \\ \hline \frac{\forall x(A(x) \wedge \exists yB(y)) \Rightarrow \forall xA(x) \wedge \exists yC(y)}{\Rightarrow \forall x(A(x) \wedge \exists yB(y)) \rightarrow \forall xA(x) \wedge \exists yC(y)} \end{array}$$

$\exists xB(x) \rightarrow \exists yC(y)$ is precondition, but also $\neg\forall xA(x)$ and $C(a)$ are preconditions. But how to calculate a weakest precondition in general?

Alternative Method

Weakest preconditions may not exist in first-order logic.

Alternative Method: Reduce first-order logic to propositional logic using **Hilbert's ε -calculus**.

Observation:

- We focus on incorrect/incomplete proofs where each quantifier inference is correct;
- Correction is only meaningful if the proofs can be written in a regular tree-like form.

Epsilon Calculus

The Birth of ε -calculus

- Hilbert & Ackermann (1925-1928) provide (**Foundations of Mathematics**) formal definition of the ε -calculus and use of ε to define quantifiers, formalize quantification via ε -terms and link logic to finitist methods.
- Key tool for formalizing consistency of analysis and finitism.
- Plays a vital role in the foundations of proof theory and formal logic.
- Eliminates the need for quantifiers syntactically.
Replace $\exists x$ and $\forall x$ with terms like $\varepsilon_x A(x)$ and $\tau_x A(x)$.
- Allows conversion of proofs to quantifier-free form (Herbrand disjunctions).
- Forms a bridge between classical and constructive reasoning.

Reactions and Alternatives

Kolmogorov (1925) **On the Principle of the Excluded Middle** -

Critique from the intuitionist perspective. Important for understanding limits of ϵ .

Skolem (1920) **Logisch-kombinatorische Untersuchungen** -

Alternative treatment of quantifiers, related to Skolem functions, which constructs functions directly without ϵ .

Gödel (1930–31) **Completeness and Incompleteness Theorems** -

Places limits on Hilbert's program via metamathematical results (final nail in the coffin of Hilbert's program — why consistency cannot be proven within the system.).

Epsilon Calculus: Basics

David Hilbert (1925-1928) (Foundations of Mathematics)

- $\varepsilon_x A(x)$: denotes a witness for x such that $A(x)$ holds if such x exists.

$$\exists x A(x) = A(\varepsilon_x A(x)), \quad \forall x A(x) = A(\varepsilon_x \neg A(x))$$

Critical Formulas:

(introduce ε -terms during substitution)

$$A(t) \rightarrow A(\varepsilon_x A(x))$$
$$A(\varepsilon_x \neg A(x)) \rightarrow A(t)$$

Translation Process:

Replace quantifiers using ε -terms recursively

$$[A]^\varepsilon \equiv A \quad A \text{ atomic}$$

$$[A \circ B]^\varepsilon \equiv [A]^\varepsilon \circ [B]^\varepsilon \quad \circ \in \{\wedge, \vee, \rightarrow\}$$

$$[\neg A]^\varepsilon \equiv \neg[A]^\varepsilon$$

$$[\exists x A(x)]^\varepsilon \equiv [A(x)]^\varepsilon \{ \varepsilon_x A(x) / x \}$$

$$[\forall x A(x)]^\varepsilon \equiv [A(x)]^\varepsilon \{ \varepsilon_x \neg A(x) / x \}$$

Example

The standard translation of $\exists x A(x) \wedge \forall x B(x)$ is $A(\varepsilon_x A(x)) \wedge B(\varepsilon_x \neg B(x))$.

Example

The standard translation of $\exists xA(x) \wedge \forall xB(x)$ is $A(\varepsilon_x A(x)) \wedge B(\varepsilon_x \neg B(x))$.

ε -expression might become complicated $[\exists x \exists y \exists z A(x, y, z)]^\varepsilon =$

$$\begin{aligned} & A(\varepsilon_x A(x, \varepsilon_y A(x, \varepsilon_z A(x, y, z))), \varepsilon_z A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), \varepsilon_z A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), \\ & \varepsilon_y A(\varepsilon_x A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), \varepsilon_z A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), \varepsilon_z A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), \\ & y, \varepsilon_z A(\varepsilon_x A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), \varepsilon_z A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), \varepsilon_z A(x, \varepsilon_y A(x, y, z))), \\ & , z)), y, z)), \varepsilon_z A(\varepsilon_x A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), \varepsilon_z A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), \varepsilon_z A(x, \varepsilon_y A(x, y, \\ & \varepsilon_z A(x, y, z))), z)), \varepsilon_y A(\varepsilon_x A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), \varepsilon_z A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, \varepsilon_y A(x, \\ & y, \varepsilon_z A(x, y, z))), z))), y, \varepsilon_z A(\varepsilon_x A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), \varepsilon_z A(x, \varepsilon_y A(x, y, \varepsilon_z A(x, \\ & \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), z))), y, z))), z))), y, z))), z))) \end{aligned}$$

Example

The standard translation of $\exists x A(x) \wedge \forall x B(x)$ is $A(\varepsilon_x A(x)) \wedge B(\varepsilon_x \neg B(x))$.

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$$A(\varepsilon_x A(x, \varepsilon_y A(x, y, z)), \varepsilon_z A(x, \varepsilon_y A(x, y, z))), \\ \varepsilon_y A(\varepsilon_x A(x, \varepsilon_y A(x, y, z)), \varepsilon_z A(x, \varepsilon_y A(x, y, z))), \\ y, \varepsilon_z A(\varepsilon_x A(x, \varepsilon_y A(x, y, z)), \varepsilon_z A(x, \varepsilon_y A(x, y, z))), \\ z), y, z), \varepsilon_z A(\varepsilon_x A(x, \varepsilon_y A(x, y, z)), \varepsilon_z A(x, \varepsilon_y A(x, y, \\ \varepsilon_z A(x, y, z))), \varepsilon_y A(\varepsilon_x A(x, \varepsilon_y A(x, y, z)), \varepsilon_z A(x, \varepsilon_y A(x, \\ y, \varepsilon_z A(x, y, z))), z), y, \varepsilon_z A(\varepsilon_x A(x, \varepsilon_y A(x, y, z)), \varepsilon_z A(x, \\ \varepsilon_y A(x, y, \varepsilon_z A(x, y, z))), y, z), z))$$

Now if we abbreviate $\exists x \forall v \exists z A(x \vee z) \stackrel{\text{E}}{=} A(e_1(e_2(e_3))) \cdot e_2(e_3) \cdot e_3$

$$[\exists x \exists y \exists z A(x, y, z)]^\varepsilon \equiv A(e_1(e_2(e_3))), e_2(e_3), e_3)$$

$$\mathbf{e}_1(y, z) \equiv \varepsilon_x A(x, y, z)$$

$$\mathbf{e}_2(z) \equiv \varepsilon_V A(\mathbf{e}_1(y, z), y, z)$$

$$\mathbf{e}_3 \equiv \varepsilon_z A(\mathbf{e}_1(\mathbf{e}_2(z)), \mathbf{e}_2(z), z)$$

Line-by-line translation of regular proofs into ε -calculus:

- Axiom sequents S become $[S]^\varepsilon$
- Structural and propositional rules are promoted unchanged
- $\exists$ -right: add $A(t) \rightarrow A(\varepsilon_x A(x))$ to antecedent
- $\forall$ -left: add $\neg A(t) \rightarrow \neg A(\varepsilon_x \neg A(x))$ to antecedent
- $\exists$ -left: substitute $a \mapsto \varepsilon_x A(x)$
- $\forall$ -right: substitute $a \mapsto \varepsilon_x \neg A(x)$

Conclusion: Valid LK-proofs lead to valid ε -proofs.

Embedding

- Since one can define quantifiers by $\exists x A(x) \equiv A_{(\varepsilon_x A(x))} \quad \forall x A(x) \equiv A_{(\varepsilon_x \neg A(x))}$. The usual quantifier rules and axioms can be derived from there.
- This definition embeds first-order logic in the ε -calculus.
- The converse is not true: not every ε/τ - formula is the image of an ordinary quantified formula under this embedding.
- Hence, the ε -calculus is more expressive than predicate calculus, simply because ε -terms can be combined in a more complex ways than quantifiers.

Embedding

Example

$$P(\varepsilon_x \neg P(x, x), \varepsilon_x \neg P(x, x)) \rightarrow P(\varepsilon_x \neg P(x, x), \underbrace{\varepsilon_y P(\varepsilon_x \neg P(x, x), y))}_e)$$

e has no meaning in first-order logic.

$$P(\varepsilon_X \neg P(x, x), \varepsilon_X \neg P(x, x)) \rightarrow \underbrace{P(\varepsilon_X \neg P(x, x), \varepsilon_Y P(\varepsilon_X \neg P(x, x), y))}_e$$

e has no meaning in first-order logic.

Key Observation:

- In ε -proofs **no eigenvariable conditions** occur.
- ε -calculus is inductive.
- Unlike usual first-order calculi, the ε -calculus admits an **unrestricted Deduction Theorem**, therefore a valid ε -proof.
- Therefore, an ε -proof of B from critical formulas

$$A_i(t_{i,j}) \rightarrow A(\varepsilon_x A_i(x))$$

is **tautology**:

$$\bigwedge_{i,j} (A_i(t_{i,j}) \rightarrow A(\varepsilon_x A_i(x))) \rightarrow B$$

P.S. ε -proof should be structurally sound (**if all critical formulas together imply the conclusion, the ε -proof is correct**).

- Bounds in ε -proof depend only on the **number of critical formulas**, not the propositional formulas.

Observation

- This translation works even for *incorrect or incomplete proofs*, where **quantifier inferences are correct**, making it possible to extract the *minimal information* needed to correct them.
- You can have wrong weak quantifier inferences and you still can translate and extract weakest precondition but you will not be able to apply ε -theorems.

• In addition to L_k possibly incorrect axioms and rules are allowed of the following form:

- In addition to L_k possibly incorrect axioms and rules are allowed of the following form:

$$\Box \Rightarrow \Gamma \quad (\text{something might be an axiom})$$

$$\frac{\begin{array}{cc} \sqcup_1 & \sqcup_2 \\ \uparrow & \uparrow \end{array}}{\sqcup} \quad \frac{\begin{array}{cc} \sqcup_1 & \sqcup_2 \\ \uparrow & \uparrow \end{array}}{\sqcup}$$

Condition: There should be no incorrect quantifier inference that lead to the wrong critical formulas.

Recall Example

Example

$$\begin{array}{c}
 \forall x(A(x) \wedge \exists yB(y)) \rightarrow \forall x(A(x) \wedge \exists xC(x)). \\
 \frac{A(a) \Rightarrow A(a) \quad \exists yB(y) \Rightarrow \exists yB(y)}{A(a) \wedge \exists yB(y) \Rightarrow A(a) \quad \exists yB(y) \Rightarrow \exists yC(y)} * \\
 \frac{\forall x(A(x) \wedge \exists yB(y)) \Rightarrow A(a) \quad A(a) \wedge \exists yB(y) \Rightarrow \exists yC(y)}{\forall x(A(x) \wedge \exists yB(y)) \Rightarrow \forall xA(x) \quad \forall x(A(x) \wedge \exists yB(y)) \Rightarrow \exists yC(y)} \\
 \frac{\forall x(A(x) \wedge \exists yB(y)) \Rightarrow \forall xA(x) \wedge \exists yC(y)}{\Rightarrow \forall x(A(x) \wedge \exists yB(y)) \rightarrow \forall xA(x) \wedge \exists yC(y)}
 \end{array}$$

$\exists xB(x) \rightarrow \exists yC(y)$ is precondition, but also $\neg \forall xA(x)$ and $C(a)$ are preconditions.

But how to calculate the weakest precondition in general?

Example

$$\begin{aligned}
 e_1 &\equiv \varepsilon_x \neg A(x) \\
 e_2 &\equiv \varepsilon_y B(y) \\
 e_3 &\equiv \varepsilon_y C(y) \\
 e_4 &\equiv \varepsilon_x \neg (A(x) \wedge B(e_2))
 \end{aligned}$$

$$\frac{A(e_1) \Rightarrow A(e_1)}{A(e_1) \wedge B(e_2) \Rightarrow A(e_1)}$$

$$\frac{B(e_2) \Rightarrow B(e_2)}{A(e_1) \wedge B(e_2) \Rightarrow B(e_2)}$$

$$\frac{A(e_1) \wedge B(e_2) \Rightarrow A(e_1) \quad A(e_1) \wedge B(e_2) \Rightarrow B(e_2)}{A(e_1) \wedge B(e_2) \Rightarrow A(e_1) \wedge B(e_2)}$$

$$\frac{A(e_1) \wedge B(e_2) \Rightarrow A(e_1) \wedge B(e_2)}{A(e_4) \wedge B(e_2) \Rightarrow A(e_1) \wedge B(e_2)}$$

$$\frac{A(e_4) \wedge B(e_2) \Rightarrow A(e_1) \wedge B(e_2)}{\Rightarrow A(e_4) \wedge B(e_2) \Rightarrow A(e_1) \wedge C(e_3)}$$

$$\mathbf{e}_1 \equiv \varepsilon_x \neg A(x)$$

$$\mathbf{e}_2 \equiv \varepsilon_y B(y)$$

$$\Theta_3 \equiv \varepsilon_Y C(Y)$$

$$\mathbf{e}_4 \equiv \varepsilon_X \neg (A(x) \wedge B(\mathbf{e}_2))$$

$$\frac{B(e_2) \Rightarrow B(e_2)}{A(e_1) \Rightarrow A(e_1) \quad B(e_2) \Rightarrow C(e_3)} * \\ \frac{A(e_1) \wedge B(e_2) \Rightarrow A(e_1) \quad A(e_1) \wedge B(e_2) \Rightarrow C(e_3)}{A(e_1) \wedge B(e_2) \Rightarrow A(e_1) \quad A(e_4) \wedge B(e_2) \Rightarrow C(e_3)} \\ \frac{A(e_4) \wedge B(e_2) \Rightarrow A(e_1) \wedge C(e_3)}{\Rightarrow A(e_4) \wedge B(e_2) \rightarrow A(e_1) \wedge C(e_3)}$$

Example

$$e_1 \equiv \varepsilon_x \neg A(x)$$

$$e_2 \equiv \varepsilon_y B(y)$$

$$e_3 \equiv \varepsilon_y C(y)$$

$$e_4 \equiv \varepsilon_x \neg (A(x) \wedge B(e_2))$$

$$\frac{\frac{\frac{A(e_1) \Rightarrow A(e_1)}{A(e_1) \wedge B(e_2) \Rightarrow A(e_1)} \quad \frac{B(e_2) \Rightarrow B(e_2)}{B(e_2) \Rightarrow C(e_3)} *}{A(e_1) \wedge B(e_2) \Rightarrow A(e_1) \wedge B(e_2) \Rightarrow C(e_3)}}{\frac{A(e_4) \wedge B(e_2) \Rightarrow A(e_1) \wedge B(e_2) \Rightarrow C(e_3)}{A(e_4) \wedge B(e_2) \Rightarrow A(e_1) \wedge C(e_3)}} \Rightarrow \frac{A(e_4) \wedge B(e_2) \Rightarrow A(e_1) \wedge C(e_3)}{\Rightarrow A(e_4) \wedge B(e_2) \rightarrow A(e_1) \wedge C(e_3)}$$

The ε -proof is

$$A(e_1) \wedge B(e_2) \rightarrow A(e_4) \wedge C(e_3) \Rightarrow A(e_4) \wedge B(e_2) \rightarrow A(e_1) \wedge C(e_3)$$

Note that this retranslation is not trivial and that no general reasonable algorithm is known.

Example

$$(A(e_1) \wedge B(e_2) \rightarrow A(e_4) \wedge C(e_3)) \Rightarrow (A(e_4) \wedge B(e_2) \rightarrow A(e_1) \wedge C(e_3))$$

A_1	B_2	C_3	A_4	$A_1 \wedge B_2 \rightarrow A_4 \wedge C_3$	$A_4 \wedge B_2 \rightarrow A_1 \wedge C_3$	Full Formula
0	0	0	0	1	1	1
0	0	0	1	1	1	1
0	0	1	0	1	1	1
0	0	1	1	1	1	1
0	1	0	0	1	1	1
0	1	0	1	1	0	0
0	1	1	0	1	1	1
0	1	1	1	1	0	0
1	0	0	0	1	1	1
1	0	0	1	1	1	1
1	0	1	0	1	1	1
1	0	1	1	1	1	1
1	1	0	0	0	0	1
1	1	0	1	0	0	1
1	1	1	0	0	0	1
1	1	1	1	1	1	1

$$A(e_1) \wedge A(e_4) \wedge B(e_2) \wedge C(e_3) \quad \forall x A(x) \wedge \forall x (A(x) \wedge \exists y B(y)) \wedge \exists x C(x)$$

Epsilon Theorems

Hilbert's Ansatz

We first present the procedure such that if we have several critical formulas belonging to the same ε -term, it allows us to eliminate these critical formulas.

Theorem: Given ε -proof π_ε of the form

$$[A(t_1) \rightarrow A(\varepsilon_x A(x)) \wedge \dots \wedge A(t_n) \rightarrow A(\varepsilon_x A(x))] \rightarrow B(\varepsilon_x A(x))$$

the resulting Hebrand's disjunction is

$$B(t_1) \vee \dots \vee B(t_n) \vee B(\varepsilon_x A(x)).$$

$\varepsilon_x A(x)$ can be replaced by one of the t_i that does not contain ε -term. In case all of the t_i contain ε -term, you can replace only by some constant. In such a way we obtain a proof π without ε -term.

Proof.

We use case distinction.

- If $A(t_1)$ holds, then replace $\varepsilon_x A(x)$ everywhere by t_1 , then $A(t_1) \rightarrow B(t_1)$. Whenever $A(t_2)$ holds, then replace $\varepsilon_x A(x)$ everywhere by t_2 and so on.
 - If all $A(t_i)$ are false then it means that $\bigwedge_i \neg A(t_i)$ is true and it implies $B(\varepsilon_x A(x))$.
- So we obtain Herbrand's disjunction
- $$B(t_1) \vee \dots \vee B(t_n) \vee B(\varepsilon_x A(x))$$
- and if $\varepsilon_x A(x)$ does not occur in one of the $A(t_i)$ we can replace it by t_i .

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Syntactic Property: Term-replacing preserves the tautological structure of ε -proof.

Example

Simple Case Consider Ansatz with two critical formulas

$$\left. \begin{array}{l} A(t) \rightarrow A(\varepsilon_x A(x)) \\ A(s) \rightarrow A(\varepsilon_x A(x)) \end{array} \right\} \rightarrow B(\varepsilon_x A(x))$$

$$\left. \begin{array}{l} A(t') \rightarrow A(t) \\ A(s') \rightarrow A(t) \end{array} \right\} \rightarrow B(t) \quad \text{gives } A(t) \rightarrow B(t)$$

$$\left. \begin{array}{l} A(t'') \rightarrow A(s) \\ A(s'') \rightarrow A(s) \end{array} \right\} \rightarrow B(s) \quad \text{gives } A(s) \rightarrow B(s)$$

If both $A(t)$ and $A(s)$ are assumed to be false, then

$$\neg A(t) \vee \neg A(s) \rightarrow B(t) \vee B(s)$$

By applying the rule of excluded middle we get:

$$B(t) \vee B(s) \vee B(\varepsilon_x A(x))$$

Extended First ε -theorem

Theorem

An ε -proof of the translation of the existential formula can be stepwise transformed into a Herbrand disjunction.

Proof.

Hilbert's Ansatz is repeatedly applied to ε -terms of maximal rank (**soundness**) and maximal degree (**termination**) and to the remaining critical formulas. $\square$

1 **Rank** - the length of the overbinding chain (subordination)

2 **Degree** - the depth of the nesting of ε -terms (inclusion)

Remark: Theorem is only suitable for derived translations of existential formulas. Other quantifiers can be replaced by Skolem functions.

Second epsilon theorem

Theorem (Second ε -theorem)

If A is a Herbrand disjunction of an existential formula after skolemization we obtain a proof of the original prenex formula.

- Skolemization is necessary to transform arbitrary formulas into existential formulas. The second ε -theorem allows to reconstruct proof of the original formulas from Herbrand's disjunction for the prenex formulas.
- Theorem holds for infix formulas: M. Baaz, S. Hetzl and D. Weller, **On the complexity of proof deskoolemization**, The Journal of Symbolic Logic, 77(2):669–686, 2012.
- The connection of the Second ε -theorem to deSkolemization procedure: M. Baaz, M. Gamsakhurdia, R. Iemhoff and R. Jalali, **Skolemization In Intermediate Logics**. (Preprint 2025)

Flow of Errors via Epsilon Calculus

Theorem

- Any ε -free propositional formula P which is implied by ε -proof, is also implied by the Herbrand disjunction obtained by the Extended first ε -theorem.
- Any ε -free propositional formula P equivalent to an ε -proof is also equivalent to Herbrand disjunction obtained by the Extended first ε -theorem.
- If disjunction of weakest preconditions $\vee F(t_i)$ which is equivalent to some ε -free propositional formula P , is equivalent to ε -proof, then it is also equivalent to its Herbrand disjunction.

Predicative ϵ -proofs

Predicative ε -proofs

Definition

An ε -proof is *predicative* iff there is at least one elimination sequence of the critical formulas $A(t) \rightarrow A(\varepsilon_x A(x))$, where $\varepsilon_x A(x)$ does not occur in t at the moment of evaluation.

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Proposition: Every formula $E(\bar{e})$ which is ε -translation of an existential formula admits a predicative ε -proof.

Proof. Calculate the Herbrand disjunction $\bigvee_i E(\vec{t}_i)$ of a non-predicative ε -proof. Recover stepwise the critical formulas from Herbrand disjunction and contract. □

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Predicative ε -proofs

Example

$$\begin{aligned} & \bigwedge_i (A(t_i) \supset A(\varepsilon_x A_i(x))) \supset E(\bar{e}) \\ & \Downarrow \\ & E(s) \vee E(t) \\ & \Downarrow \\ & (A(s) \supset A(\varepsilon_x A(x)) \wedge A(t) \supset A(\varepsilon_x A(x))) \supset E(\bar{e}) \end{aligned}$$

Critical Formulas

Number theories can be expressed using two types of critical formulas

- **Standard critical formulas:**

$$A(t) \rightarrow A(\varepsilon_x A(x))$$

- **Inductive critical formulas:**

$$A(t) \rightarrow A(\varepsilon_x A(x) \leq t)$$

False-Tolerance

False-Tolerance

Theorem

The algorithm of the extended first ε -theorem is false-tolerant: If an ε -proof fails under exactly one interpretation (one line in its minimal truth table), then its extracted Herbrand disjunction also fails under exactly one interpretation.

- Preserves the degree of failure.
- Resulting Herbrand disjunction may be syntactically longer.
- The Herbrand disjunction is not necessarily incorrect when the ε -proof is incorrect, it may actually be correct:

Example

$(A(t) \supset A(e)) \supset (A(e) \supset A(t))$ with t not containing e , is not correct, but its Herbrand disjunction $A(t) \supset A(t)$ is correct.

Summary

- ε -calculus: remove quantifiers via witnesses.
- False-tolerance: preserves the degree of errors.
- Applications: incorrect/incomplete proofs in **mathematics** and Ratio Decidendi in **English Common Law**.

Conclusion

Most relevant question: what is the retranslation of an ε -expressions to first-order expressions?

$$P(\varepsilon_X \neg P(x, x), \varepsilon_X \neg P(x, x)) \rightarrow P(\varepsilon_X \neg P(x, x), \varepsilon_Y \underbrace{P(\varepsilon_X \neg P(x, x), y)}_e)$$

e has no meaning in first-order logic. Any satisfying answer implies the solution to the **problem of T. Arai**: **Is there an elementary retranslation of LK^ε -proofs with cuts in LK -proofs with cuts?**

Further Reading

- Avigad, J. and Zach, R. "The Epsilon Calculus," *Stanford Encyclopedia of Philosophy*, 2013. <https://plato.stanford.edu/entries/epsilon-calculus/>
- M. Baaz, M. Gamsakhurdia - "Towards a Proof-Theoretic Analysis of Incorrect Proofs" - in proceedings of LOGICA 2025 (tba)
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Thank you!